

Probabilistic Structural Analysis Using Matrix Variate Distributions

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Stochastic structural dynamics

- The equation of motion:

$$\mathbf{M}\ddot{\mathbf{x}}(t) + \mathbf{C}\dot{\mathbf{x}}(t) + \mathbf{K}\mathbf{x}(t) = \mathbf{p}(t)$$

- Due to the presence of uncertainty \mathbf{M} , \mathbf{C} and \mathbf{K} become random matrices.
- The objective is to quantify uncertainties in the response vector \mathbf{x} .

Current Methods

Three different approaches are currently available

- Low frequency : Stochastic Finite Element Method (SFEM) - considers parametric uncertainties in details
- High frequency : Statistical Energy Analysis (SEA) - do not consider parametric uncertainties in details
- Mid-frequency : Hybrid method - ‘combination’ of the above two

Random Matrix Method (RMM)

- **The objective**: To have a simple **unified method** which will work across the frequency range.
- **The methodology**:
 - Derive the matrix variate probability density functions of M , C and K
 - Propagate the uncertainty (using Monte Carlo simulation or analytical methods) to obtain the response statistics (or pdf)

Outline of the presentation

In what follows next, I will discuss:

- Introduction to Matrix variate distributions
- ‘Maximal uncertain’ distribution
- Distributions under inverse moment constraints
- Optimal Wishart distribution
- Response statistics using Wishart distribution
- Numerical examples
- Open problems & discussions

Matrix variate distributions

- The probability density function of a random matrix can be defined in a manner similar to that of a random variable.
- If \mathbf{A} is an $n \times m$ real random matrix, the matrix variate probability density function of $\mathbf{A} \in \mathbb{R}_{n,m}$, denoted as $p_{\mathbf{A}}(\mathbf{A})$, is a mapping from the space of $n \times m$ real matrices to the real line, i.e., $p_{\mathbf{A}}(\mathbf{A}) : \mathbb{R}_{n,m} \rightarrow \mathbb{R}$.

Gaussian random matrix

The random matrix $\mathbf{X} \in \mathbb{R}_{n,p}$ is said to have a matrix variate Gaussian distribution with mean matrix $\mathbf{M} \in \mathbb{R}_{n,p}$ and covariance matrix $\Sigma \otimes \Psi$, where $\Sigma \in \mathbb{R}_n^+$ and $\Psi \in \mathbb{R}_p^+$ provided the pdf of \mathbf{X} is given by

$$p_{\mathbf{X}}(\mathbf{X}) = (2\pi)^{-np/2} |\Sigma|^{-p/2} |\Psi|^{-n/2} \operatorname{etr} \left\{ -\frac{1}{2} \Sigma^{-1} (\mathbf{X} - \mathbf{M}) \Psi^{-1} (\mathbf{X} - \mathbf{M})^T \right\} \quad (1)$$

This distribution is usually denoted as $\mathbf{X} \sim N_{n,p}(\mathbf{M}, \Sigma \otimes \Psi)$.

Gaussian orthogonal ensembles

A random matrix $\mathbf{H} \in \mathbb{R}_{n,n}$ belongs to the Gaussian orthogonal ensemble (GOE) provided its pdf of is given by

$$p_{\mathbf{H}}(\mathbf{H}) = \exp \left(-\theta_2 \text{Trace} (\mathbf{H}^2) + \theta_1 \text{Trace} (\mathbf{H}) + \theta_0 \right)$$

where θ_2 is real and positive and θ_1 and θ_0 are real. This is a good model for high-frequency vibration problems.

Wishart matrix

An $n \times n$ random symmetric positive definite matrix \mathbf{S} is said to have a Wishart distribution with parameters $p \geq n$ and $\Sigma \in \mathbb{R}_n^+$, if its pdf is given by

$$p_{\mathbf{S}}(\mathbf{S}) = \left\{ 2^{\frac{1}{2}np} \Gamma_n \left(\frac{1}{2}p \right) |\Sigma|^{\frac{1}{2}p} \right\}^{-1} |\mathbf{S}|^{\frac{1}{2}(p-n-1)} \text{etr} \left\{ -\frac{1}{2}\Sigma^{-1}\mathbf{S} \right\} \quad (2)$$

This distribution is usually denoted as $\mathbf{S} \sim W_n(p, \Sigma)$.

Note: If $p = n + 1$, then the matrix is non-negative definite.

Matrix variate Gamma distribution

An $n \times n$ random symmetric positive definite matrix \mathbf{W} is said to have a matrix variate gamma distribution with parameters a and $\Psi \in \mathbb{R}_n^+$, if its pdf is given by

$$p_{\mathbf{W}}(\mathbf{W}) = \left\{ \Gamma_n(a) |\Psi|^{-a} \right\}^{-1} |\mathbf{W}|^{a - \frac{1}{2}(n+1)} \text{etr} \{-\Psi \mathbf{W}\}; \quad \Re(a) > (n-1)/2 \quad (3)$$

This distribution is usually denoted as $\mathbf{W} \sim G_n(a, \Psi)$. Here the multivariate gamma function:

$$\Gamma_n(a) = \pi^{\frac{1}{4}n(n-1)} \prod_{k=1}^n \Gamma \left[a - \frac{1}{2}(k-1) \right]; \quad \text{for } \Re(a) > (n-1)/2 \quad (4)$$

Distribution of the system matrices

The distribution of the random system matrices \mathbf{M} , \mathbf{C} and \mathbf{K} should be such that they are

- symmetric
- positive-definite, and
- the moments (at least first two) of the inverse of the dynamic stiffness matrix

$$\mathbf{D}(\omega) = -\omega^2\mathbf{M} + i\omega\mathbf{C} + \mathbf{K} \text{ should exist } \forall \omega$$

Maximum Entropy Distribution

Suppose that the mean values of \mathbf{M} , \mathbf{C} and \mathbf{K} are given by $\overline{\mathbf{M}}$, $\overline{\mathbf{C}}$ and $\overline{\mathbf{K}}$ respectively. Using the notation \mathbf{G} (which stands for any one of the system matrices) the matrix variate density function of $\mathbf{G} \in \mathbb{R}_n^+$ is given by $p_{\mathbf{G}}(\mathbf{G}) : \mathbb{R}_n^+ \rightarrow \mathbb{R}$. We have the following constraints to obtain $p_{\mathbf{G}}(\mathbf{G})$:

$$\int_{\mathbf{G}_{>0}} p_{\mathbf{G}}(\mathbf{G}) d\mathbf{G} = 1 \quad (\text{normalization}) \quad (5)$$

$$\text{and} \quad \int_{\mathbf{G}_{>0}} \mathbf{G} p_{\mathbf{G}}(\mathbf{G}) d\mathbf{G} = \overline{\mathbf{G}} \quad (\text{the mean matrix})$$

(6)

MEnt Distribution - 1

The Lagrangian to be maximised:

$$\begin{aligned} \mathcal{L}(p_{\mathbf{G}}) = & - \int_{\mathbf{G} > 0} p_{\mathbf{G}}(\mathbf{G}) \ln \{p_{\mathbf{G}}(\mathbf{G})\} d\mathbf{G} + \\ & (\lambda_0 - 1) \left(\int_{\mathbf{G} > 0} p_{\mathbf{G}}(\mathbf{G}) d\mathbf{G} - 1 \right) \\ & + \text{Trace} \left(\Lambda_1 \left[\int_{\mathbf{G} > 0} \mathbf{G} p_{\mathbf{G}}(\mathbf{G}) d\mathbf{G} - \overline{\mathbf{G}} \right] \right) \quad (7) \end{aligned}$$

$\lambda_0 \in \mathbb{R}$ and $\Lambda_1 \in \mathbb{R}_{n,n}$ are the unknown Lagrange multipliers to be determined.

MEnt Distribution - 2

Using the calculus of variation

$$\frac{\partial \mathcal{L}(p_{\mathbf{G}})}{\partial p_{\mathbf{G}}} = 0$$

or $(\lambda_0 - 1) + \text{Trace}(\Lambda_1 \mathbf{G}) - (1 + \ln \{p_{\mathbf{G}}(\mathbf{G})\}) = 0$

or $-\ln \{p_{\mathbf{G}}(\mathbf{G})\} = \lambda_0 + \text{Trace}(\Lambda_1 \mathbf{G})$

or $p_{\mathbf{G}}(\mathbf{G}) = \exp\{-\lambda_0\} \text{etr}\{-\Lambda_1 \mathbf{G}\}$

(8)

MEnt Distribution - 3

Substituting into the constraint equations results

$$p_{\mathbf{G}}(\mathbf{G}) = r^{nr} \{\Gamma_n(r)\}^{-1} |\overline{\mathbf{G}}|^{-r} \text{etr} \left\{ -r \overline{\mathbf{G}}^{-1} \mathbf{G} \right\} \quad (9)$$

where $r = \frac{1}{2}(n + 1)$. Comparing, it can be observed that \mathbf{G} has the Wishart distribution with parameters $p = n + 1$ and $\Sigma = \overline{\mathbf{G}}/(n + 1)$.

Theorem 1. *If only the mean of a system matrix $\mathbf{G} \equiv \{\mathbf{M}, \mathbf{C}, \mathbf{K}\}$ is available, say $\overline{\mathbf{G}}$, then the matrix has a Wishart distribution with parameters $(n + 1)$ and $\overline{\mathbf{G}}/(n + 1)$, that is $\mathbf{G} \sim W_n(n + 1, \overline{\mathbf{G}}/(n + 1))$.*

Further constraints

- Suppose the inverse moments (say up to order ν) of the system matrix exist. This implies that $E \left[\left\| \mathbf{G}^{-1} \right\|_F^\nu \right]$ should be finite. Here the Frobenius norm of matrix \mathbf{A} is given by
$$\| \mathbf{A} \|_F = \left(\text{Trace} \left(\mathbf{A} \mathbf{A}^T \right) \right)^{1/2} .$$
- Taking the logarithm for convenience, the condition for the existence of the inverse moments can be expressed by

$$E \left[\ln \left| \mathbf{G} \right|^{-\nu} \right] < \infty$$

MEnt Distribution - Again!

The new Lagrangian becomes:

$$\begin{aligned} \mathcal{L}(p_{\mathbf{G}}) = & - \int_{\mathbf{G} > 0} p_{\mathbf{G}}(\mathbf{G}) \ln \{p_{\mathbf{G}}(\mathbf{G})\} d\mathbf{G} + \\ & (\lambda_0 - 1) \left(\int_{\mathbf{G} > 0} p_{\mathbf{G}}(\mathbf{G}) d\mathbf{G} - 1 \right) - \nu \int_{\mathbf{G} > 0} \ln |\mathbf{G}| p_{\mathbf{G}} d\mathbf{G} \\ & + \text{Trace} \left(\Lambda_1 \left[\int_{\mathbf{G} > 0} \mathbf{G} p_{\mathbf{G}}(\mathbf{G}) d\mathbf{G} - \overline{\mathbf{G}} \right] \right) \quad (10) \end{aligned}$$

Note: ν cannot be obtained uniquely!

MEnt Distribution - 2A

Using the calculus of variation

$$\frac{\partial \mathcal{L}(p_{\mathbf{G}})}{\partial p_{\mathbf{G}}} = 0$$

or $-\ln \{p_{\mathbf{G}}(\mathbf{G})\} = \lambda_0 + \text{Trace}(\Lambda_1 \mathbf{G}) - \ln |\mathbf{G}|^\nu$

or $p_{\mathbf{G}}(\mathbf{G}) = \exp\{-\lambda_0\} |\mathbf{G}|^\nu \text{etr}\{-\Lambda_1 \mathbf{G}\}$

We use the matrix variate Laplace transform:

$$\int_{\Lambda > 0} \text{etr}\{-\Lambda \mathbf{Z}\} |\Lambda|^{a-(p+1)/2} d\Lambda = \Gamma_p(a) |\mathbf{Z}|^{-a}$$

MEnt Distribution - 3A

Substituting into the constraint equations we have:

Theorem 2. *If ν -th order inverse moment of a system matrix \mathbf{G} exists and only the mean is available, say $\overline{\mathbf{G}}$, then the matrix has a Wishart distribution with parameters $(2\nu + n + 1)$ and $\overline{\mathbf{G}}/(2\nu + n + 1)$, that is*

$$\mathbf{G} \sim W_n(2\nu + n + 1, \overline{\mathbf{G}}/(2\nu + n + 1)).$$

Note that $\nu = 0$ gives us the ‘maximal uncertain distribution’ derived before.

Properties of the Distribution

- Covariance tensor of \mathbf{G} :

$$\text{cov} (G_{ij}, G_{kl}) = \frac{1}{2\nu + n + 1} (\overline{G}_{ik}\overline{G}_{jl} + \overline{G}_{il}\overline{G}_{jk}) \quad (11)$$

- Normalized standard deviation matrix

$$\text{E} [(\mathbf{G} - \overline{\mathbf{G}})^2] \overline{\mathbf{G}}^{-2}:$$

$$\sigma_{\mathbf{G}}^2 = \frac{1}{2\nu + n + 1} \left[\mathbf{I}_n + \overline{\mathbf{G}}^{-1} \text{Trace} (\overline{\mathbf{G}}) \right] \quad (12)$$

- $\nu \uparrow \Rightarrow \sigma_{\mathbf{G}}^2 \downarrow$.

Distribution of the inverse - 1

- If \mathbf{G} is $W_n(p, \Sigma)$ then $\mathbf{V} = \mathbf{G}^{-1}$ has the inverted Wishart distribution:

$$P_{\mathbf{V}}(\mathbf{V}) = \frac{2^{m-n-1} n/2 |\Psi|^{m-n-1} / 2}{\Gamma_n[(m-n-1)/2] |\mathbf{V}|^{m/2}} \text{etr} \left\{ -\frac{1}{2} \mathbf{V}^{-1} \Psi \right\}$$

where $m = n + p + 1$ and $\Psi = \Sigma^{-1}$ (recall that $p = 2\nu + n + 1$ and $\Sigma = \overline{\mathbf{G}}/p$)

Distribution of the inverse - 2

- Mean: $E[\mathbf{G}^{-1}] = \frac{p\bar{\mathbf{G}}^{-1}}{p - n - 1}$
- Normalized standard deviation matrix

$$E\left[\left(\mathbf{G}^{-1} - \bar{\mathbf{G}}^{-1}\right)^2\right] \bar{\mathbf{G}}^2:$$

$$\sigma_{\mathbf{G}^{-1}}^2 = \frac{(p - n - 1)}{(p - n)(p - n - 3)} \left[\mathbf{I}_n + \bar{\mathbf{G}} \text{Trace} \left(\bar{\mathbf{G}}^{-1} \right) \right] \quad (13)$$

Distribution of the inverse - 3

- Suppose $n = 101$ & $\nu = 2$. So $p = 2\nu + n + 1 = 106$ and $p - n - 1 = 4$. Therefore, $E[\mathbf{G}] = \overline{\mathbf{G}}$ and $E[\mathbf{G}^{-1}] = \frac{106}{4} \overline{\mathbf{G}}^{-1} = 26.5 \overline{\mathbf{G}}^{-1}$!!!!!!!!!!!!!
- Of course there is no reason why $E[\mathbf{G}^{-1}] = \overline{\mathbf{G}}^{-1}$. But from a practical point of view do we expect them to be so far apart?
- One way to reduce the gap is to increase p . But this implies reduction of variance.

Some questions

- What do we really need: $E[G] = \bar{G}$ or $E[G^{-1}] = \bar{G}^{-1}$ or any other powers.
- \bar{G} is just one 'observation' - not an ensemble mean.
- What happens if we know the covariance tensor of G (e.g., using Stochastic Finite element Method)?
- What if the zeros in G are not preserved?

Optimal Wishart Distribution - 1

- Suppose $\mathbf{G} \sim W_n(m, \Sigma)$ and $\mathbf{A} \in \mathbb{R}_n^+$ is the deterministic value of a system matrix.
- **My argument:** The distribution of \mathbf{G} must be such that $E[\mathbf{G}]$ and $E[\mathbf{G}^{-1}]$ should be closest to \mathbf{A} and \mathbf{A}^{-1} respectively.
- Therefore, define (and subsequently minimize)

‘normalized errors’:

$$\boldsymbol{\varepsilon}_1 = [\mathbf{A} - E[\mathbf{G}]] \mathbf{A}^{-1} \in \mathbb{R}_n$$

$$\boldsymbol{\varepsilon}_2 = [\mathbf{A}^{-1} - E[\mathbf{G}^{-1}]] \mathbf{A} \in \mathbb{R}_n$$

Optimal Wishart Distribution - 2

- Obtain m and Σ such that $\chi^2 = \|\boldsymbol{\varepsilon}_1\|_F^2 + \|\boldsymbol{\varepsilon}_2\|_F^2 = \text{Trace}(\boldsymbol{\varepsilon}_1\boldsymbol{\varepsilon}_1^T) + \text{Trace}(\boldsymbol{\varepsilon}_2\boldsymbol{\varepsilon}_2^T)$ is minimized.
- Suppose $m = n + 1 + \theta$ and $\Sigma = \mathbf{A}\mathbf{X}$. Using these we have $\boldsymbol{\varepsilon}_1 = [\mathbf{I}_n - (n + 1 + \theta)\mathbf{X}]$ and $\boldsymbol{\varepsilon}_2 = [\mathbf{I}_n - \{\theta\mathbf{X}\}^{-1}]$
- Since $\Sigma = \Sigma^T$ and $\mathbf{A} = \mathbf{A}^T$, we have $\mathbf{A}\mathbf{X} = \mathbf{X}^T\mathbf{A}$ or $\mathbf{X}^T = \mathbf{A}\mathbf{X}\mathbf{A}^{-1}$
- Set $\frac{\partial\chi^2}{\partial\theta} = 0$ and $\frac{\partial\chi^2}{\partial\mathbf{X}} = \mathbf{O}$. Total $n^2 + 1$ unknowns and $n^2 + 1$ equations - can be solved.

Optimal Wishart Distribution - 3

We obtain

$$\begin{aligned} & \theta^4 \text{Trace}(\mathbf{XAXA}^{-1}) \\ & + \theta^3 \{ (n+1) \text{Trace}(\mathbf{XAXA}^{-1}) - \text{Trace}(\mathbf{X}) \} \\ & + \theta \text{Trace}(\mathbf{X}^{-1}) - \text{Trace}(\mathbf{X}^{-1} \mathbf{A} \mathbf{X}^{-1} \mathbf{A}^{-1}) = 0 \end{aligned} \quad (14)$$

$$\mathbf{AXA}^{-1} + \mathbf{A}^{-1} \mathbf{X} \mathbf{A} = \frac{2\mathbf{I}_n}{n+1+\theta} - \boldsymbol{\xi}(\theta, \mathbf{X}) \quad (15)$$

$$\begin{aligned} \boldsymbol{\xi}(\theta, \mathbf{X}) = & (n+1+\theta)^{-2} [2\theta^{-1} \mathbf{X}^{-2} \\ & + \theta^{-2} \mathbf{X}^{-1} [\mathbf{AX}^{-1} \mathbf{A}^{-1} + \mathbf{A}^{-1} \mathbf{X}^{-1} \mathbf{A}] \mathbf{X}^{-1}] \end{aligned} \quad (16)$$

Optimal Wishart Distribution - 4

Use iteration to solve the coupled nonlinear scalar-matrix equations

1. Start with $\theta = 2$, $\mathbf{X} = \mathbf{I}_n / (n + 1 + \theta)$
2. Solve θ from the fourth order equation (14)
3. Obtain \mathbf{X}_{new} from (by taking $\text{vec}(\bullet)$ of Eq. (15))

$$[\mathbf{A}^{-1} \otimes \mathbf{A} + \mathbf{A} \otimes \mathbf{A}^{-1}] \text{vec}(\mathbf{X}_{new}) = \frac{2\mathbf{I}_n}{n + 1 + \theta} \text{vec}(\mathbf{I}_n) - \text{vec}(\boldsymbol{\xi}(\theta, \mathbf{X}))$$

4. If $\|\mathbf{X}_{new} - \mathbf{X}\|_F < \text{'small number'}$ then stop. Otherwise, set $\mathbf{X} = \mathbf{X}_{new}$ and go back to step 2.

Response statistics - 1

- The equation of motion is $\mathbf{D}\mathbf{x} = \mathbf{p}$, \mathbf{D} is in general $n \times n$ complex random matrix.
- The response is given by

$$\mathbf{x} = \mathbf{D}^{-1}\mathbf{p}$$

- Consider **static** problems so that all matrices/vectors are real.

Response statistics - 2

- We may want statistics of few elements or some linear combinations of the elements in \mathbf{x} . So the quantify of interest is

$$\mathbf{y} = \mathbf{R}\mathbf{x} = \mathbf{R}\mathbf{D}^{-1}\mathbf{p} \quad (17)$$

Here \mathbf{R} is in general $r \times n$ rectangular matrix. For the special case when $\mathbf{R} = \mathbf{I}_n$, we have $\mathbf{y} = \mathbf{x}$.

- Eq. (17) arises in SFEM. There are many papers on its solution. Mainly perturbation methods are used.

Response statistics - 3

Suppose $\mathbf{D} = \mathbf{D}_0 + \Delta\mathbf{D}$, where \mathbf{D}_0 is the deterministic part and $\Delta\mathbf{D}$ is the (small) random part. It can be shown that

$$\mathbf{D}^{-1} = \mathbf{D}_0^{-1} - \mathbf{D}_0^{-1} \Delta\mathbf{D} \mathbf{D}_0^{-1} + \mathbf{D}_0^{-1} \Delta\mathbf{D} \mathbf{D}_0^{-1} \Delta\mathbf{D} \mathbf{D}_0^{-1} - \dots$$

From, this

$$\mathbf{y} = \mathbf{y}_0 - \mathbf{R} \mathbf{D}_0^{-1} \Delta\mathbf{D} \mathbf{x}_0 + \mathbf{R} \mathbf{D}_0^{-1} \Delta\mathbf{D} \mathbf{D}_0^{-1} \Delta\mathbf{D} \mathbf{x}_0 - \dots \quad (18)$$

where $\mathbf{x}_0 = \mathbf{D}_0^{-1} \mathbf{p}$ and $\mathbf{y}_0 = \mathbf{R} \mathbf{x}_0$.

Response statistics - 4

The statistics of y can be calculated from Eq. (18). However,

- The calculation is difficult if ΔD is non-Gaussian.
- Even if ΔD is Gaussian, inclusion of higher-order terms results very messy calculations (I have not seen any published work for more than second-order)
- For these reasons, the response statistics will be inaccurate for large randomness.

Response statistics - 5

I will propose an **exact** method using RMM.

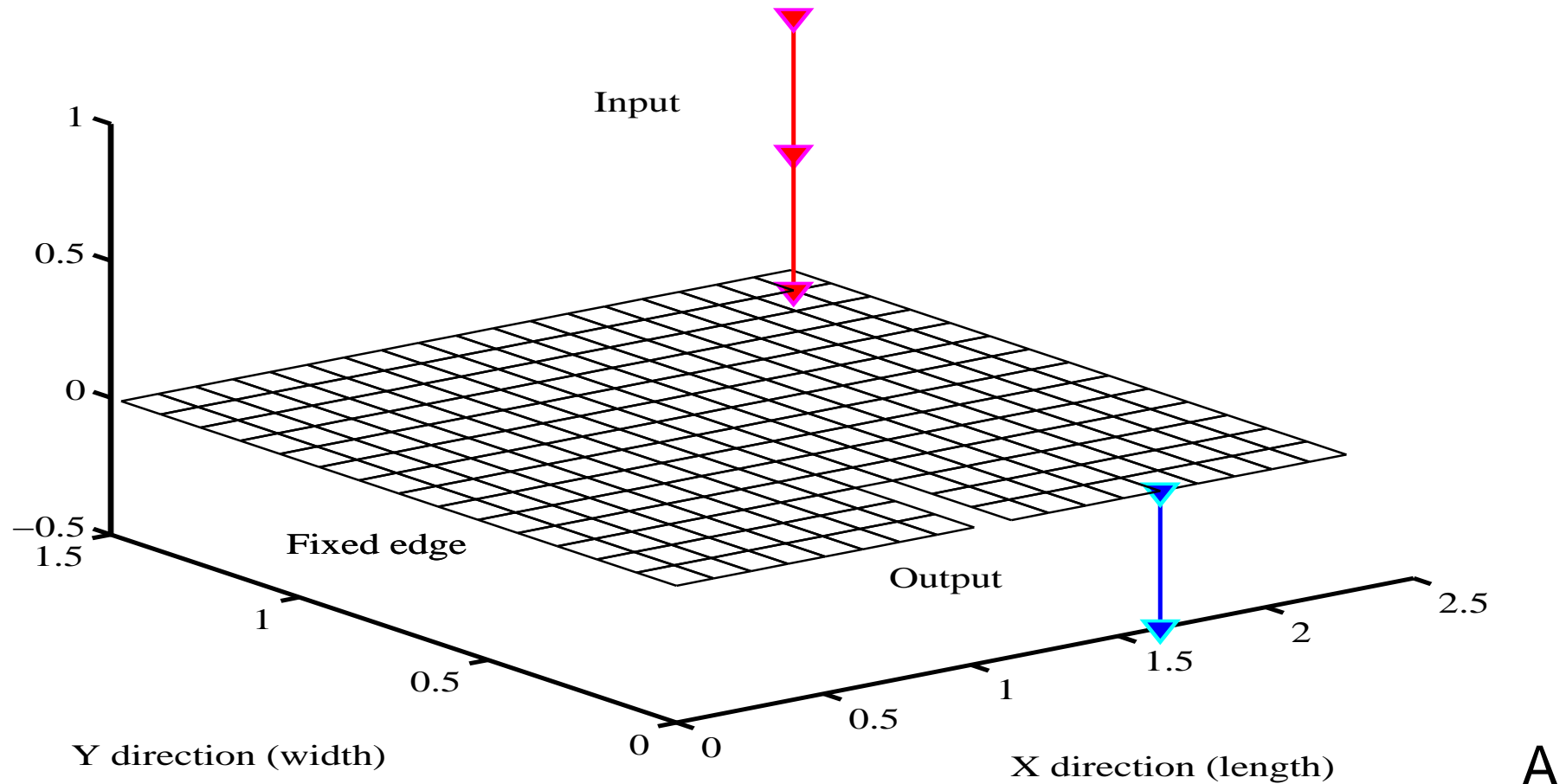
Suppose $\mathbf{D} \sim W_n(m, \Sigma)$.

$$E[\mathbf{y}] = E[\mathbf{R}\mathbf{D}^{-1}\mathbf{p}] = \mathbf{R}E[\mathbf{D}^{-1}]\mathbf{p} = \mathbf{R}\Sigma^{-1}\mathbf{p}/\theta \quad (19)$$

The complete covariance matrix of \mathbf{y}

$$\begin{aligned} & E[(\mathbf{y} - E[\mathbf{y}])(\mathbf{y} - E[\mathbf{y}])^T] \\ &= \mathbf{R}E[\mathbf{D}^{-1}\mathbf{p}\mathbf{p}^T\mathbf{D}^{-1}]\mathbf{R}^T - E[\mathbf{y}](E[\mathbf{y}])^T \\ &= \frac{\text{Trace}(\Sigma^{-1}\mathbf{p}\mathbf{p}^T)\mathbf{R}\Sigma^{-1}\mathbf{R}^T}{\theta(\theta+1)(\theta-2)} + \frac{(\theta+2)\mathbf{R}\Sigma^{-1}\mathbf{p}\mathbf{p}^T\Sigma^{-1}\mathbf{R}^T}{\theta^2(\theta+1)(\theta-2)} \end{aligned} \quad (20)$$

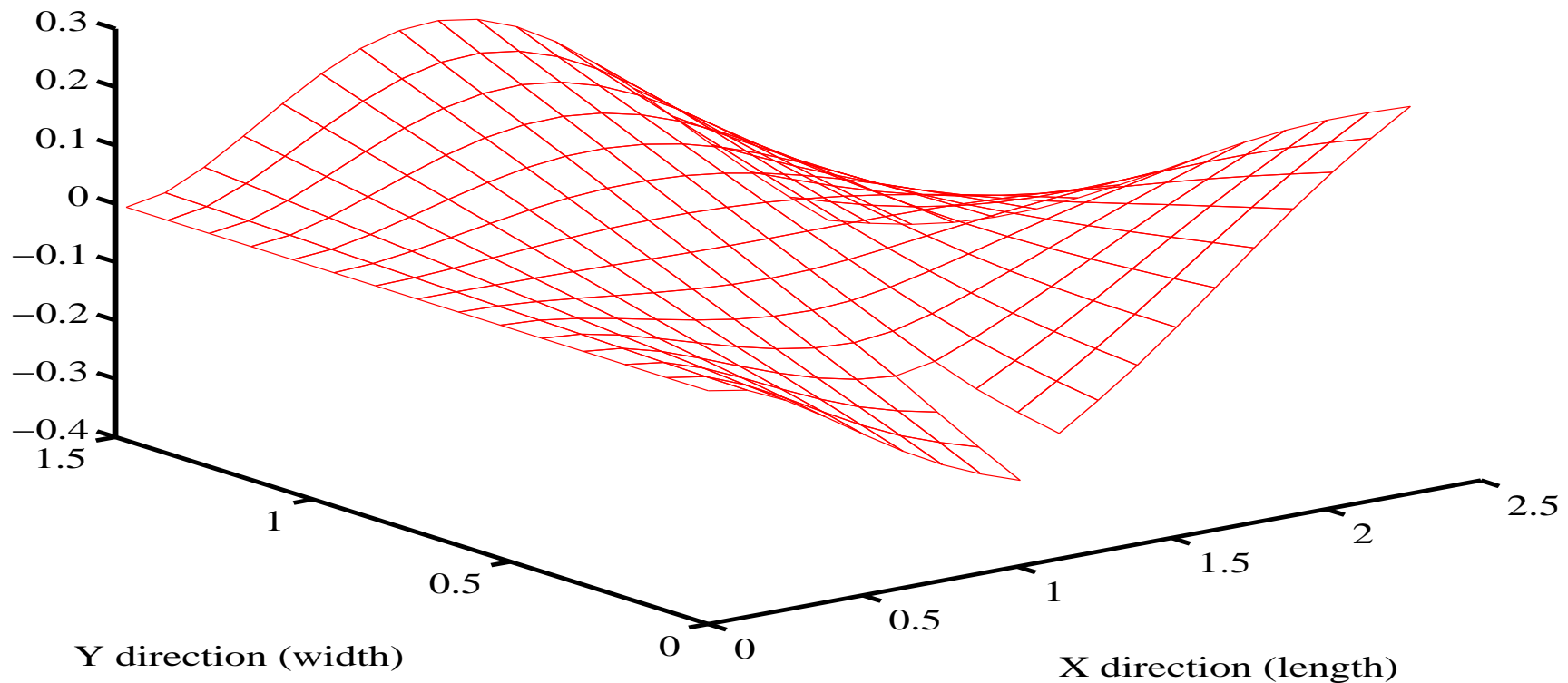
Example: A cantilever Plate



Cantilever plate with a slot: $\mu = 0.3$, $\rho = 8000 \text{ kg/m}^3$, $t = 5\text{mm}$,
 $L_x = 2.27\text{m}$, $L_y = 1.47\text{m}$

Plate Mode 4

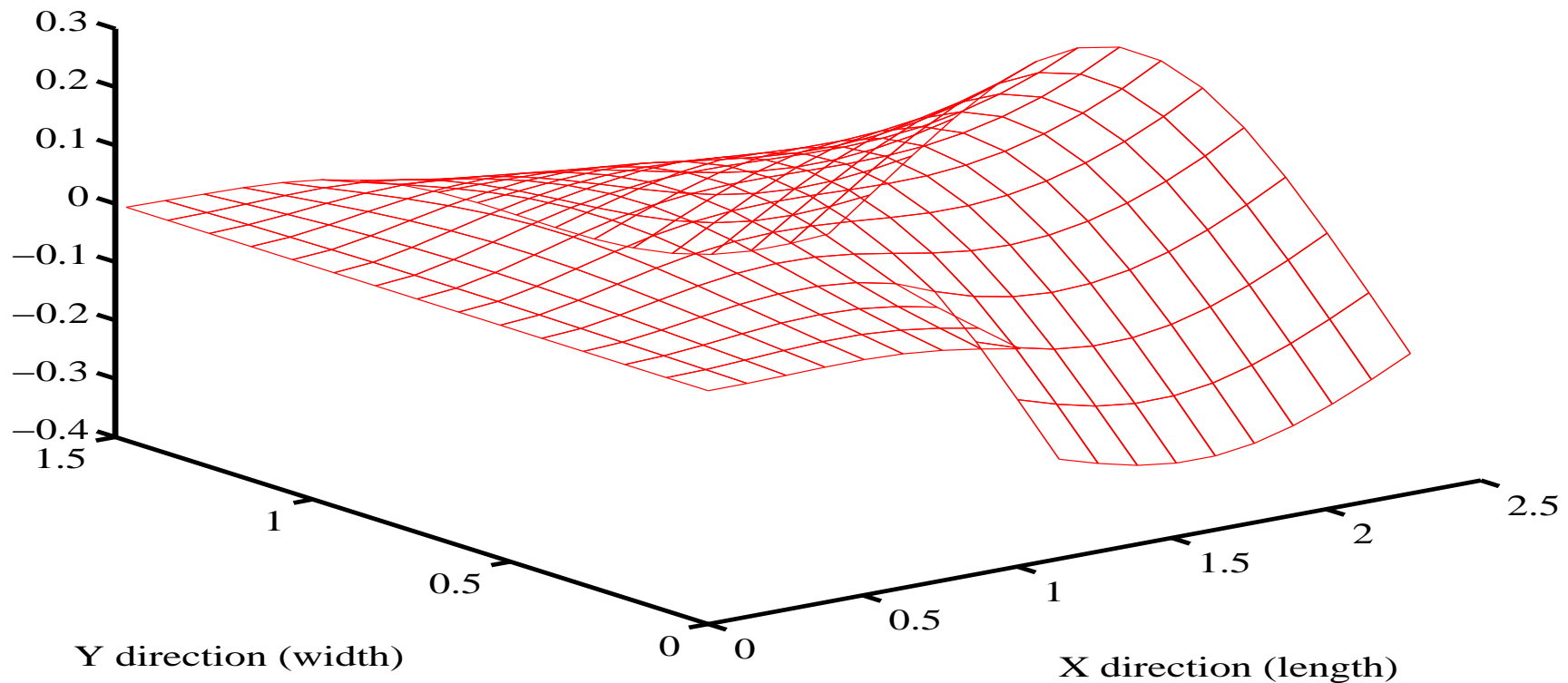
Mode 4, freq. = 9.2119 Hz



Fourth Mode shape

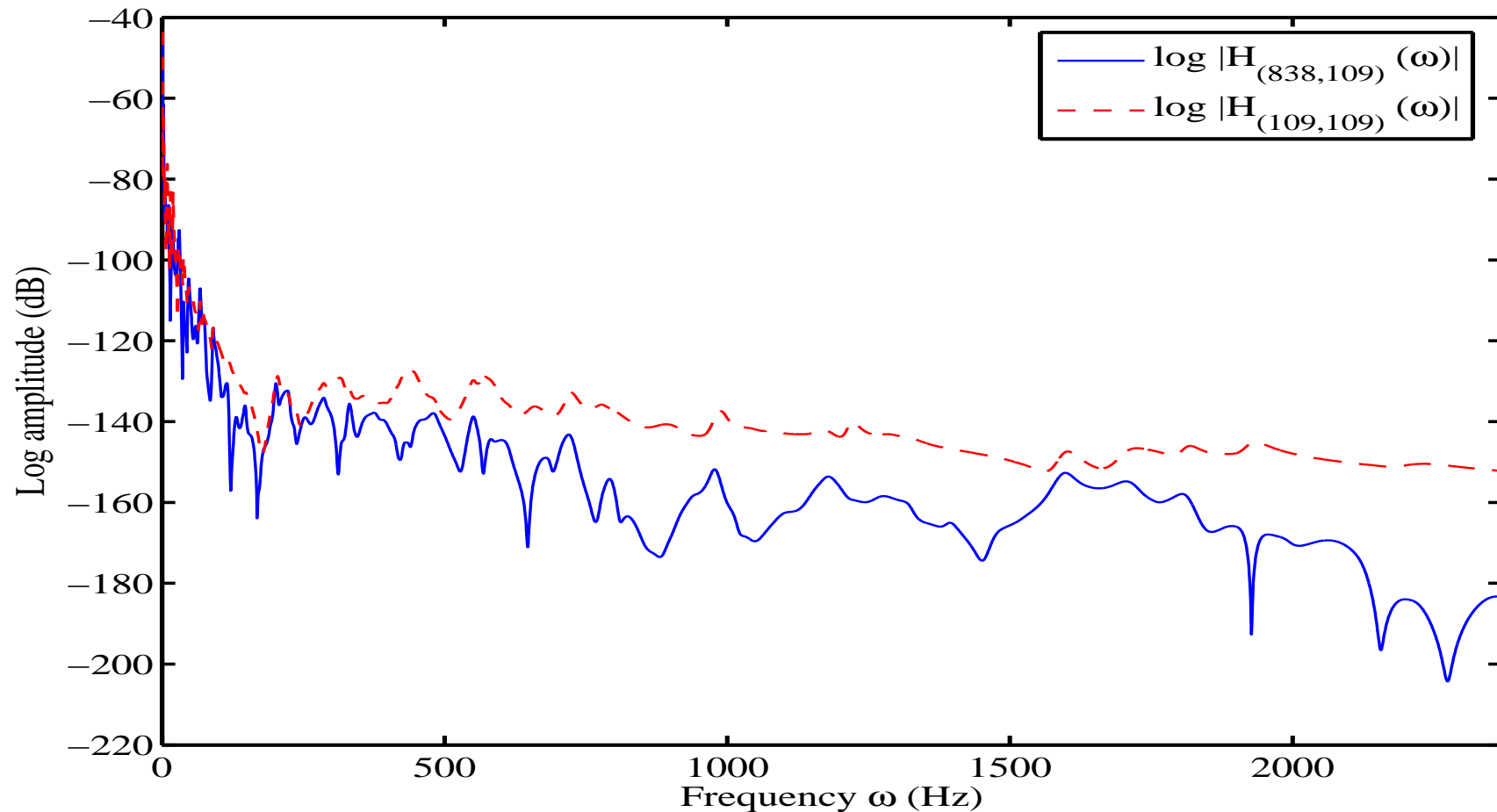
Plate Mode 5

Mode 5, freq. = 11.6696 Hz



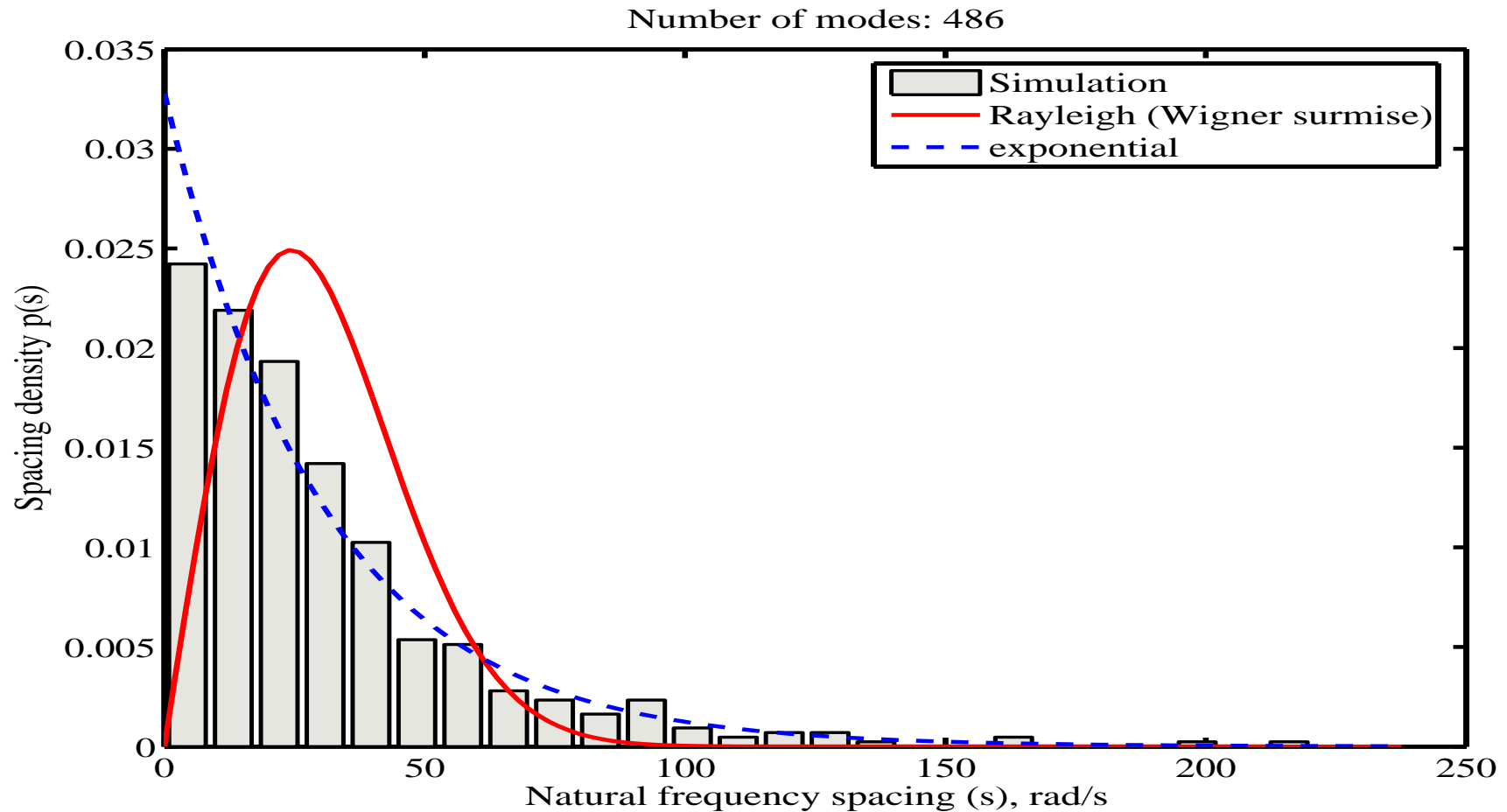
Fifth Mode shape

Deterministic FRF



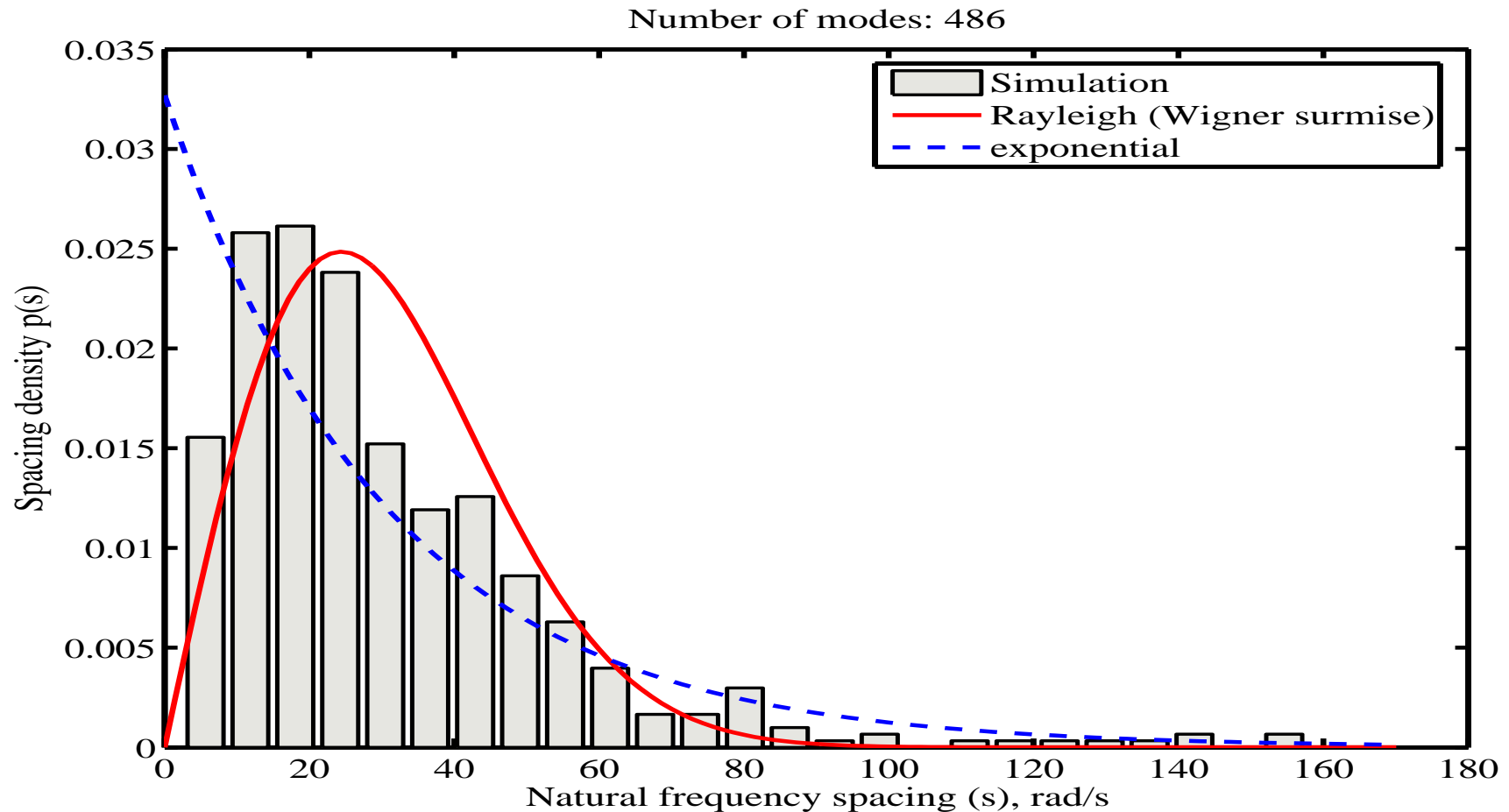
FRF of the deterministic plate

Frequency Spacing



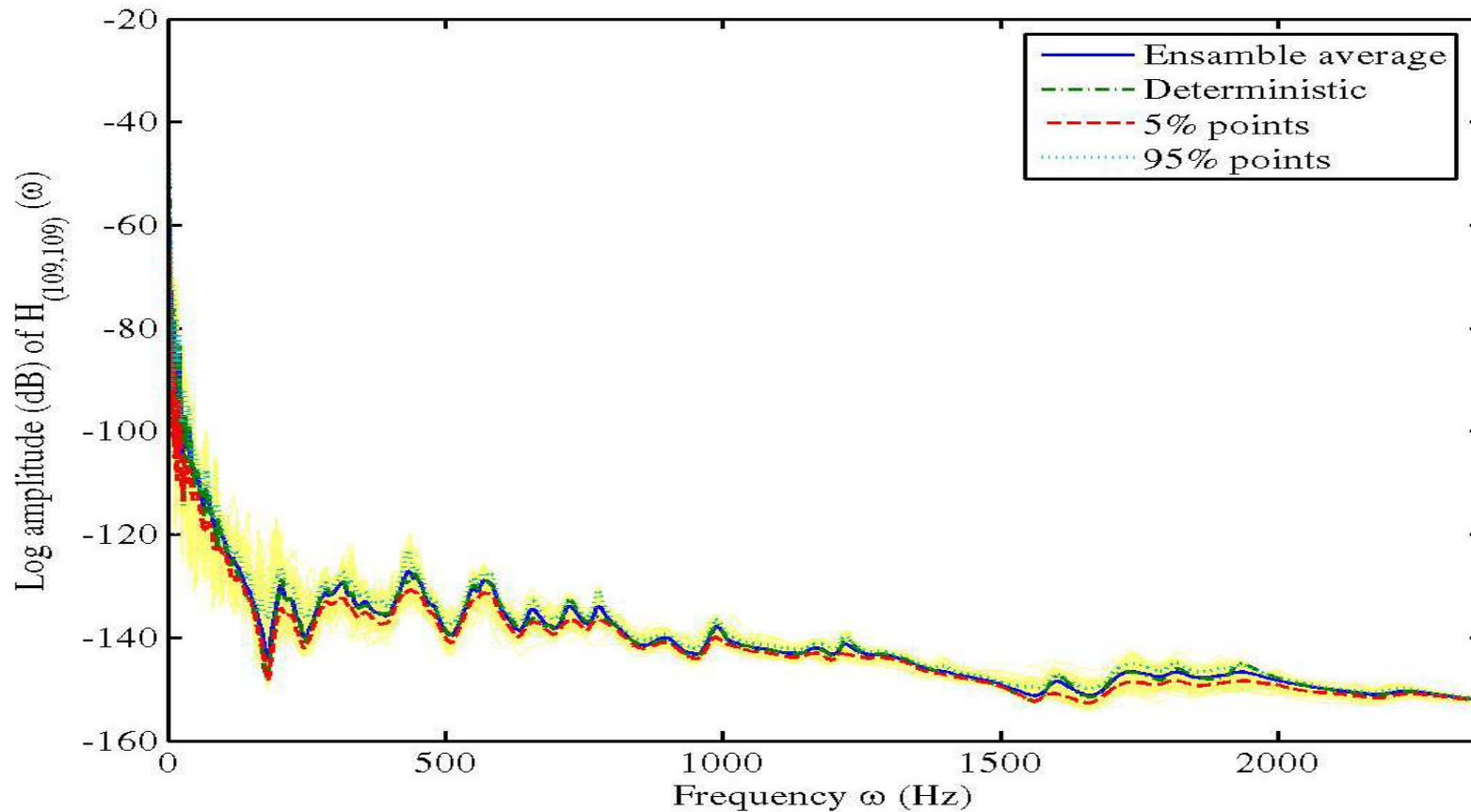
Natural frequency spacing distribution (**without slot**)

Frequency Spacing



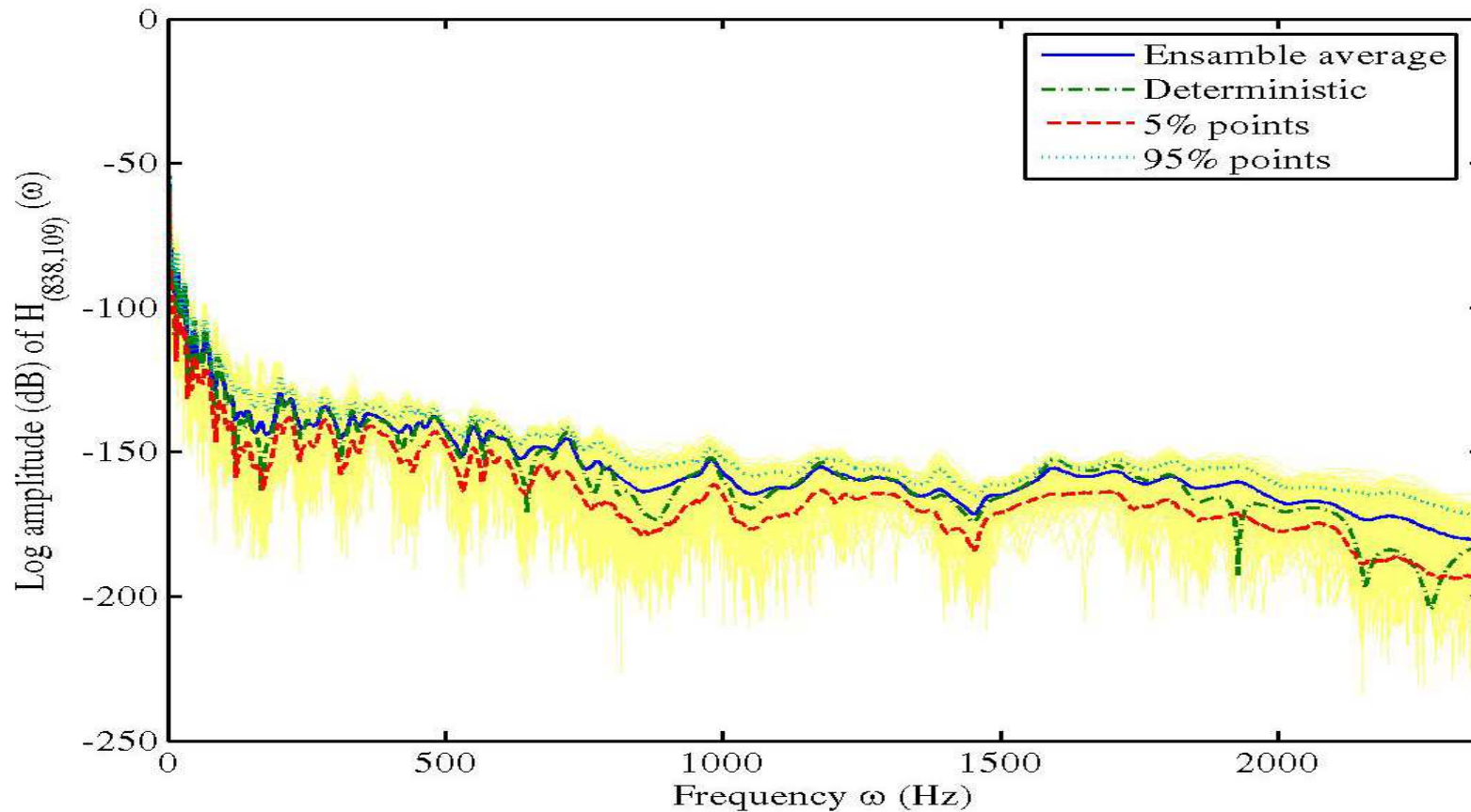
Natural frequency spacing distribution (**with slot**)

Random FRF - 1



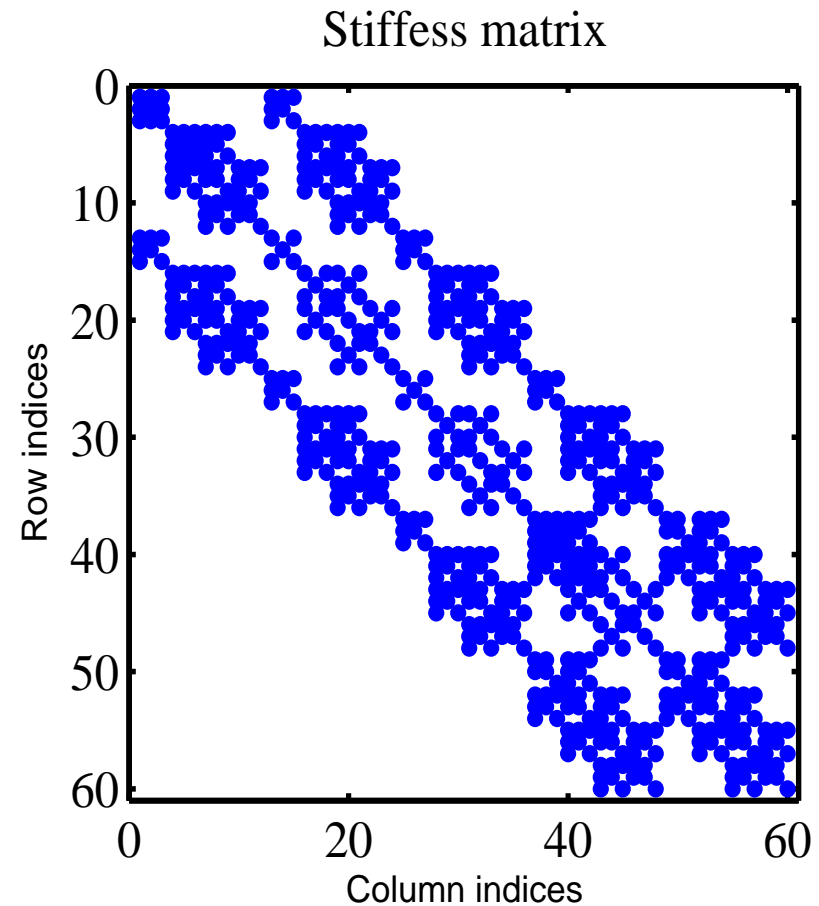
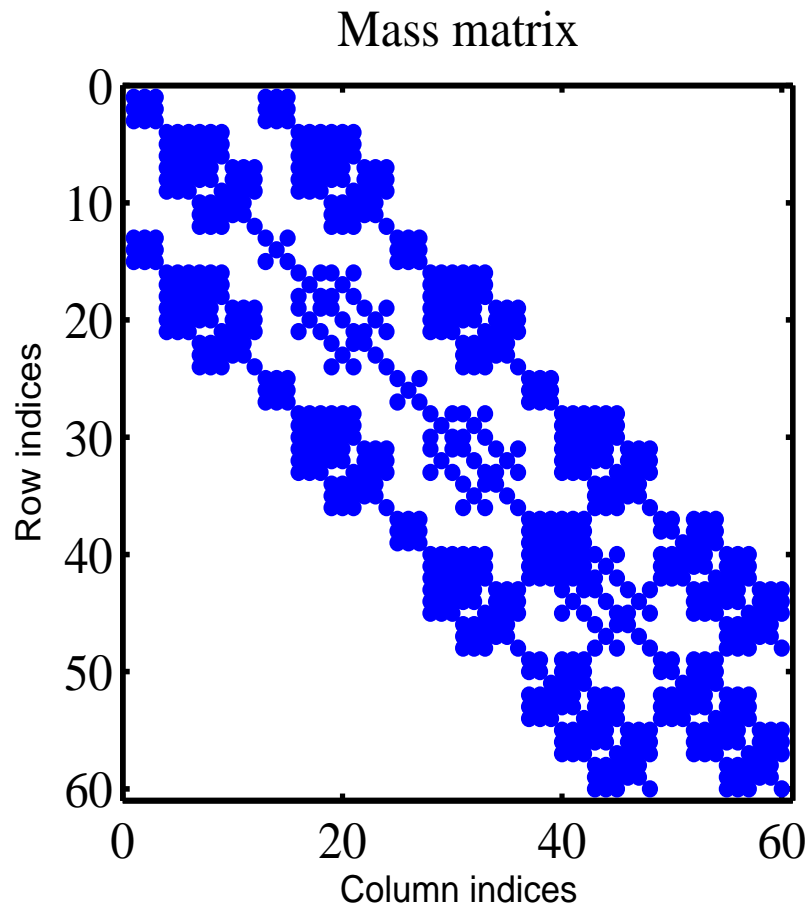
Driving point FRF using optimal Wishart distribution

Random FRF - 2



A cross FRF using optimal Wishart distribution

Structure of the Matrices



Nonzero elements of the system matrices

Summary & conclusions

- **Wishart matrices** can be used as the distribution for the system matrices in structural dynamics.
- The parameters of the distribution can be obtained by solving an optimisation problem

Next steps

- Numerical works (validation against??)
- Distribution of the dynamic stiffness matrix (complex Wishart matrix?)
- Inversion of the dynamic stiffness matrix (FRFs)
- Distribution of $\mathbf{Y}(\omega) = [\mathbf{R}\mathbf{D}(\omega)^{-1}\mathbf{P}]$ where $\mathbf{P} \in \mathbb{C}_{n,r}$ and $\mathbf{R} \in \mathbb{R}_{p,n}$
- Eigenvalues, eigenvector statistics and calculation of dynamic response.
- Cumulative distribution function of the response

Open problems & discussions

- Structure preserving random matrices (low-mid frequency?)
- Non-central Wishart matrices (preservation of covariance structure - parametric uncertainty models?)
- Solution of SFEM using RMT (connection with polynomial chaos expansions)?
- Eigenvalue problem, Wigner surmise
- Analytical expression of the pdf of dynamic response
- Energy statistics - SEA